# Notes on Signal to Noise Ratio

M.Lampton FUEGO Team Space Sciences Lab UC Berkeley May 2012; Jan and April 2014

### **Quantum Efficiency and Responsivity**

- **Quantum Efficiency QE**: 0<QE<1 is the probability that an incoming photon produces an electron output from a pixel
- Responsivity is that same concept, except put into amperes per watt rather than electrons per photon:
- **Responsivity R** =  $(q_{electron} / hc) \cdot QE \cdot \lambda_{microns}$  where 0<QE<1

= 0.807  $\cdot QE \cdot \lambda_{microns}$  amperes per watt

- Responsivity is used when converting an incident pixel scene power (watts) into sensor current, or accumulated charge in exposure time T<sub>exp</sub>
- Signal output current  $I_{sig} = R \cdot P_{sig} = Responsivity_{A/W} \cdot P_{sig}$
- Signal output charge  $Q_{sig} = R \cdot P_{sig} \cdot T_{exp} = Responsivity_{A/W} \cdot E_{sig}$

### Signal to Noise Ratio and NEP from Current Noise

- Suppose a sensor system is perfectly steady: no pointing jitter
- Suppose its scene is steady plus some small signal to be detected
- The output current of a pixel will be  $I = I_{dark} + R \cdot (P_{scene} + P_{signal}) \pm I_{rms}$ 
  - R = Responsivity of pixel, in amperes per watt
  - P = P<sub>scene</sub> + P<sub>signal</sub> = radiant power within Δλ arriving at the pixel, in watts
  - I<sub>rms</sub> is the root mean square noise in the pixel current measurement
- Here, I<sub>DC</sub> = dark + scene currents are assumed perfectly subtractible
  - from many statistically independent estimates over time and space
- For one sample,  $I_{rms}$  = pixel current noise
  - This is the one-sigma current measurement uncertainty for one pixel, one sample
- Noise Equivalent Power: **NEP**  $\equiv$  Prms = I<sub>rms</sub> / Responsivity
- Signal to Noise Ratio: **SNR** =  $P_{signal}/NEP$  = Responsivity  $\cdot P_{signal}/I_{rms}$

## **Two Models for Photodetector Heat Environment**

assuming now that detector is cold enough that Idark is negligible



- Uniform scene, T=300K, **spatially** fills pixel diode area Apix
- Uniform scene heat fills optical **solid angle** Ωpix, typically 0.01 to 1 ster
- **Cold** camera interior (e.g. IR astronomy): no other added heat or noise.
- or **Warm** camera interior:  $2\pi$  hemisphere, 300K,  $\Omega$  eff= $\pi$  ster.

### **Thermal contrast and NEDT for Photodiodes**

- Given noise Irms, **NEP** = Irms/Responsivity = Irms/(dI/dP)
- Use slope dI/dT of Planck law: **NEDT** = Trms = Irms/(dI/dT)

Thermal contrast is the relative change in thermal flux for a one kelvin change in temperature.



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# Shot Noise $I_{rms}$ from $I_{DC}$

- There are many causes of noise: 1/f, microphonics, shot noise
- Shot noise dominates in high-brightness situations
- Shot noise is the statistically independent random arrivals of electrons
  - Steady dark current, if any
  - Steady current from camera interior heat, if any
  - Steady scene current
- The Poisson distribution describes the accumulation of random arrivals
- The variance of the Poisson distribution equals its mean
- $N_{rms} = v(N_{mean}) = v(I_{DC} \cdot T_{exp} / q_{electron})$
- $Q_{rms} = V(I_{DC} \cdot T_{exp} \cdot q_{electron})$
- $I_{rms} = Q_{rms} / T_{exp} = V(I_{DC} \cdot q_{electron} / T_{exp})$
- This is often recast in terms of bandwidth  $B=1/(2T_{exp})$ :
- $I_{rms} = v(2 I_{DC} \cdot q_{electron} \cdot B)$

#### Relationships for thermal photons, current, noise

Cold Camera: use  $\Omega = \Omega$ optical; Warm Camera use  $\Omega = \pi$  steradians. Astronomers use cold cameras to make the second term negligibly small. Both cases here: I ignore dark current, i.e. the pixels themselves are plenty cold.

Photon arrival rate: pixel area A, optical solid angle  $\Omega$ , and waveband  $\Delta \lambda$ :

$$N = A \cdot \Omega \cdot \Delta \lambda \cdot \frac{2c}{\lambda^4 \cdot (exp(hc/\lambda kT) - 1)}$$

Total DC =  $I_{scene} + I_{camera}$  given  $QE_{opt}$ ,  $T_{scene}$ ,  $QE_{diode}$  and  $T_{camera}$ :

$$I_{dc} = \frac{q \cdot QE_{opt} \cdot A \cdot \Omega \cdot \Delta\lambda_{opt} \cdot 2c}{\lambda^4 \cdot (exp(hc/\lambda kT_{scene}) - 1)} + \frac{q \cdot QE_{diode} \cdot A \cdot \pi \cdot \Delta\lambda_{diode} \cdot 2c}{\lambda^4 \cdot (exp(hc/\lambda kT_{camera}) - 1)}$$

RMS current noise for an integrating exposure time  $\tau_{exp} = 1/(2B_{Hz})$ :

$$I_{rms} = (2qI_{dc}B_{Hz})^{0.5} = (qI_{dc}/\tau_{exp})^{0.5}$$

Derivative of current with respect to scene temperature:

$$\frac{dI_{scene}}{dT_{scene}} = I_{scene} \cdot \frac{hc \cdot exp(hc/\lambda kT_{scene})}{\lambda kT_{scene}^2 \cdot (exp(hc/\lambda kT_{scene}) - 1)}$$

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## **Specific Detectivity D\***

- NEP<sub>watts</sub> is the incoming power at a pixel required to yield SNR=1
  - for a microbolometer,  $15\mu m$  pixel, 100Hz: NEP  $\approx$  1E-10 watts.
- Detectivity D = 1/NEP = Responsivity/I<sub>rms</sub>
- Usually, I<sub>rms</sub> is proportional to square root of pixel area A
  - Dark current is linearly proportional to A, other things being equal
  - Scene current is linearly proportional to A, other things being equal
- Usually, I<sub>rms</sub> is proportional to square root of electrical bandwidth B
- Specific Detectivity D\* factors out these two proportionalities:
- $D^* = D \cdot \sqrt{A} \cdot \sqrt{B} = \sqrt{A} \cdot \sqrt{B} / NEP$ 
  - for a microbolometer,  $D^* \approx 1E8$  cm rootHz/watt.
- In this way, D\* describes the sensivity of a sensor normalized to a common bandwidth (1 Hz) and a common area (1 cm2)
- D\* is then is a material property dependent on wavelength, temperature, and radiative scene environment, but not dependent on integration time, bandwidth, or pixel size.
- $D^*$  has units of cm VHz / watt.

# Using D\* to get SNR for bolometers

- Signal to noise ratio SNR = Psignal/Pnoise
- Pnoise =  $1/D = \sqrt{A} \cdot \sqrt{B}/D^*$
- So... SNR = Psignal D\* /( $VA \cdot VB$ )
- If a microbolometer has pixel size  $17\mu m$ , VA = 0.00017 cm
- If a microbolometer has 100 frames/sec, VB = 7 VHz
- If a microbolometer has D\* = 1E8 cm rootHz/W, then
- SNR = Psignal/Pnoise with Pnoise=10<sup>-10</sup> watts.

#### Scene Irradiance in Three Wavebands



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# A Warm Microbolometer Model

based on the LETI/IR-FPA model

INEDT, K	0.054
Pixel, µm	17
EBW, Hz	100
Rth, K/W	1.0E+08
TCR, per K	0.03
TempResponsivity V/K	0.011
therefore Vnoise, V	5.94E-04
FillFactor	0.60
Absorption Effic	0.60
PowerResponsivity V/W	4.0E+05
NEP=Vn/R, W	1.50E-09
D*. cm VHz/W	1.13E+07





# A Cold Photodiode Warm Camera Model

- Pixel size 15  $\mu$ m;  $\Omega$ view =  $\pi$  ster
- Dark current is entirely due to half space *heat* within camera
- This photon flux is the Planck law shortward of sensor cutoff : Nph=6E18 ph/m2.s.ster @ 4µm.
- DarkRate = Nph · Apix · Ωview = 4E9 events/sec.pixel
- RMS =  $\sqrt{\text{Rate} \cdot \text{Texp}}$  photons
- NEP =signal at  $\lambda$  that gives a net photon count = RMS photons in Texp, i.e. NEP= (hc/  $\lambda$ ) · RMS/Texp
- NEP =  $(hc/\lambda) \cdot \sqrt{\pi}$  Nph Apix /Texp)
- NEP =  $(hc/\lambda) \cdot \sqrt{2\pi}$  Nph Apix B)
- D\*=2.5E11 cm √Hz/W at 4µm.



#### **D\* Values for a wide variety of IR detectors: 300K Half Space**



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## Of course for very sensitive work...

- Never flood your detector with heat!
- Always use a cold stop to block stray instrument heat!
- Keep the sensor environment as cold as possible!
- etc
- etc
- and after all that, it is best to model each heat source and combine the results to predict the system sensitivity.



#### References to Current Work

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